# OMS11 Outdoor Modem Switch Installation and Operation Manual

TM133 Revision 1.1



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#### **Comtech EF Data Corporation**

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# Preface



This manual provides installation and operation information for the Radyne OMS11 1:1 Redundancy Switch. This is a technical document intended for use by engineers, technicians, and operators responsible for the operation and maintenance of the OMS11.

#### Conventions

Whenever the information within this manual instructs the operator to press a pushbutton switch or keypad key on the Front Panel, the pushbutton or key label will be shown in "less than" (<) and "greater than" (>) brackets. For example, the Reset Alarms Pushbutton will be shown as <RESET ALARMS>, while a command that calls for the entry of a '7' followed by 'ENTER' Key will be represented as <7,ENTER>.

#### **Cautions and Warnings**



A caution icon indicates a hazardous situation that if not avoided, may result in minor or moderate injury. Caution may also be used to indicate other unsafe practices or risks of property damage.



A warning icon indicates a potentially hazardous situation that if not avoided, could result in death or serious injury.



A note icon identifies information for the proper operation of your equipment, including helpful hints, shortcuts, or important reminders.

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#### **Record of Revisions**

Revision Level	Date	Reason for Change	
1.0	11-30-07	Initial Release	
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#### **Comments or Suggestions Concerning this Manual**

Comments or suggestions regarding the content and design of this manual are appreciated. To submit comments, please contact the Comtech EF Data Corporation Customer Service Department.



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## Introduction



#### 1.0 Description

The Radyne OMS11 Outdoor Modem Switch provides redundancy protection for the OM20 Outdoor Modem, BUC and LNB. The OMS11 offers redundancy support for OM20 user data, Asynchronous data, RS485 and BUC/LNB Waveguide Switching control. The OMS11 redundancy system is based on a Chain switching system that switches the IF/RF primary path to the IF/RF Backup path. Optional BUCs, LNBs, Waveguide Switches and Mounting hardware are optional items that can be supplied with the system. Contact Radyne for supported hardware options. Refer to Figure 1-1 for an illustration of the OMS11 1:1 Redundancy Switch Front Panel and Figure 1-3 of an OMS11 Functional Block Diagram.

Operating in the Automatic Mode, the OMS11 immediately places a Backup Modem and IF/RF Path online in the event of a Primary Modem/IF/RF path fails. The OMS11 chain switches the modem, BUC and LNB. In the Manual Mode, the user may designate the selected Online Primary Modem from either the Interactive Front Panel or a remote Terminal Interface. The backup functions of the OMS11 may be performed manually via the front panel or the RS485, RLLP remote protocol or the RS232 Terminal port.



Figure 1-1 OMS11 1:1 Redundancy Switch Front Panel

## 1.1 Redundant Power Supplies

The OMS11 is equipped with two fully redundant internal power supplies. Each power supply is independent of the other, including their source of AC or DC input source. The OMS11 remains fully operational as long as either power supply is providing a source of power. The power supplies are internal to the OMS11 Chassis.

#### **1.2 Front Panel Controls**

The Front Panel of the OMS11 provides all of the necessary controls and LED indicators to provide the operator with online status and backup status of the online and backup OM20 Modems.

# 1.3 Power-Up Defaults

During power-up, the OMS11 initializes itself to the last mode set by the Front Panel Pushbuttons.



# Theory of Operation



#### 2.0 Theory of Operation

The Radyne OMS11 Outdoor Modem Switch provides redundancy protection for the OM20 Outdoor Modem, BUC and LNB. The OMS11 redundancy system is based on a Chain switching system that switches the IF/RF primary path to the IF/RF Backup path. The Chain Switching system can includes BUCs, LNBs, Waveguide, Waveguides Switches, mounting hardware and connecting cables. BUCs, LNBs, Waveguide Switches and Mounting hardware are optional items that can be supplied with the system. Refer to Figure 1-1 for an illustration of the OMS11 1:1 Redundancy Switch Front Panel and Figure 2-1 for the OMS11 Functional Block Diagram.

The BUC and LNB switch over fault detection system is primarily done by the OM20 Modem. When the OM20 is configured to supply power to the BUC and LNB, the modem uses internal detection circuitry to monitor current and voltage status of the BUC and LNB. User must properly set up the BUC/LNB voltage and current threshold limits on the OM20. Refer to the OM20 user manual for proper set.

In cases where the BUCs are powered by an external power supply, fault detection can be detected by the OM20 only if the BUC includes Normally Closed contact closures. In order to support BUC redundancy, the BUC must have Normally Closed Contact closures available for the OMS11/OM20 to support redundancy.

## 2.1 OMS11 Operation

A block diagram of the signal flow is shown in Figure 2-1 below.

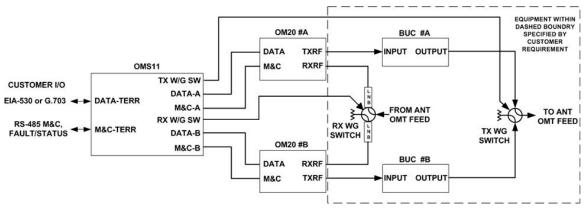


Figure 2-1 Functional Block Diagram

## 2.1.1 Operating Procedures

The OMS11 is designed to require minimal operator intervention and control during normal operation. After initial setup, the unit should operate in a relatively 'transparent' manner, providing trouble-free backup of the online Modems. The scope of this section is limited to instruction on the various modes of control available to the operator. Refer to Section 3-1 for the OMS11 Front Panel Controls and Indicators and Table 2-1 for a description of the Controls and Indicators.

## 2.1.2 Configuring the OMS11

The redundancy switch must be properly configured prior to operation. Date interface type, Remote communication type and remote baud rate must be set correctly to meet the users needs. Configuring these options can only be done by removing the cover and accessing the dip switches on the board. Appendix A of this manual gives specific information about the dip switch settings for configuring the Terminal and Remote ports. If you need assistance with the settings, contact Radyne customer service department.

## 2.1.3 Front Panel Controls (Refer to Figure 2-1)

The purpose of the 'ENABLE' pushbutton on the front panel is to reduce the risk of accidentally changing the operating modes of the OMS11 by accidentally bumping any one of the front panel pushbuttons. For any one of the front panel pushbuttons to function, the 'ENABLE' pushbutton must be depressed simultaneously with the desired function pushbutton. Depress the 'ENABLE' pushbutton. This pushbutton must be depressed to allow the operator to proceed with any other configurations. The 'MANUAL' LED should illuminate and the FAULT indicator may momentarily flash. Under the MOD region of the front panel, depress 'SELECT A' to bring Modem 'A' modulator online. The green LED should illuminate. Under the DEMOD region of the front panel, depress 'SELECT A' to bring modem 'A' modulator online. The green LED should illuminate. The Green LED should illuminate. The Green LED should illuminate.

#### 2.1.4 Manual Mode

To manually select which Modem is to be placed online, simultaneously depress the 'ENABLE' pushbutton and the appropriate Modem 'SELECT' pushbutton. When a Modem selection is made, the OMS11 enters Manual Mode to carry out the selection, and will not respond to either modem's Modem Fault signals until placed back into Auto Mode.

## 2.1.5 Auto Mode

To enable automatic backup in the event of a Modem failure, the OMS11 must be placed into the Auto Mode. First, select which Modem that will be active by following the 'Manual Mode' procedure in the previous paragraph. To enter the Auto Mode, simultaneously depress the 'ENABLE' pushbutton and the 'SELECT AUTO' pushbutton. The OMS11 will then enter into Auto Mode with the last selections made in Manual Mode. In the Auto Mode, the decision to switch from one Modem to another is made automatically by monitoring the Fault signals from each modem.

## 2.1.6 Power-Up Defaults

During power-Up, the OMS11 initializes itself to the last mode set by the operator on the front panel pushbuttons.

#### 2.2 OMS11 Major Assemblies

The OMS11 Redundancy Control Unit contains the modules that control and monitor the operation of the 1:1 Switch system. The 1:1 Switch is composed of the following major assemblies and components:

Main Switch Board Waveguide Switch Board Front Panel Dual (Redundant) Power Supplies

#### 2.2.1 Main Switch Board

The Main Switch Board contains the OMS11 1:1 Switch Intelligence and Memory Circuitry and all switching circuitry. The microprocessor controls and coordinates all of the major functions of the Switch and performs all necessary calculations. The non-volatile system memory on the board stores the switching parameter settings for each modem channel. Control and data signals are routed to the appropriate devices in the system through various latches and transceivers that are controlled by the microprocessor.

#### 2.2.2 Front Panel

The Front Panel contains the LED Indicators and the pushbutton switches needed to control and operate the OMS11. Refer to Figure 3.0 for a description of Front Panel Indicators.

#### 2.2.3 Redundant Power Supplies

The 1:1 Switch comes equipped with two fully redundant internal power supplies (PS1 and PS2) that supplies power to the switch and external switching components. Each supply is fully independent of the other, including their source of AC/DC power and fusing. The Switch can remain fully operational as long as it is supplied with a source of voltage from either power supply.

#### 2.3 OMS11 General Operation

#### 2.3.1 Data Signals

Modem data signals are backed-up through a passive switching system. Signals that are required to maintain the modem in off-line (hot-standby) are buffered by appropriate circuitry to minimize loading on incoming signals.

#### 2.3.2 Backup

If an online Modem fault is sensed, and the off-line Modem is in a non-faulted state, the OMS11 will switch to the Modem without the fault. The Fault Signal has a small debounce delay to prevent false triggering. If the faulted Modem has its fault cleared, it stays off-line unless the other MODEM has subsequently faulted.

#### 2.3.3 Fail-Safe

If the OMS11 has a non-recoverable internal fault, the switch will revert back to Modem A, the Switch Fault LED is illuminated, and the Switch Fault Relay switches to a faulted state.

If Power Supply 1 and Power Supply 2 simultaneously fail, the switching circuitry in the OMS11 reverts back to Modem A, and the Switch Fault Relay switches to a faulted state. Modem B does not receive buffered signals in this condition.

#### 2.3.4 OMS11 Fault Relays

The OMS11 M&C Connector (J8) has Form-C contacts available that indicate modem online and OMS11 Fault status. Refer to section for additional information.

#### 2.4 Fault Detection

The OMS11 & OM20 work simultaneously to determine the status of all the components within this system. The OMS11 & OM20 are capable of monitoring BUC and LNB redundancy system. Faults detection is established by the OM20 and forwarded to the OMS11. Fault detection for a redundant BUC system will be different based on whether the BUC Power is supplied by the OM20 or if the BUC Power is supplied by an external power source. If the BUC power is supplied externally, then the BUC must have Normally Closed Form C Fault contacts so the OMS11/OM20 can monitor the BUC fault status.

#### Fault detection with the OM20 supplying power to BUC:

- BUC Faults OM20 uses internal fault detection circuitry to determine BUC status and initiates a fault that is forwarded to the OMS11
- OM20 uses internal fault detection circuitry to determine LNB status and initiate fault

#### Fault detection with BUC power supplied externally:

- BUC must have Normally Closed Form C contacts in order for BUC fault detection to work
- OM20 data cable CAR5902 or CAR5918 has an external connector that is used to connect and monitor Form C Contacts from the BUC.
- OM20 uses internal fault detection circuitry to determine LNB status and initiate fault



# **User Interfaces**



#### 3.0 User Interfaces

These are:

- Front Panel Interface Refer to Section 3.1.
- Remote Interface Refer to Appendix B.



Figure 3-1 OMS11 Front Panel

Table 3-1. OMS11 Front Panel Controls and Indicators			
Nomenclature	Description	Function	
Power 1	Indicates PS1 has power applied	LED illuminates Green for Power Available	
Power 2	Indicates PS2 has power applied	LED illuminates Green for Power Available	
Fault	Indicates a Switch Fault has occurred	LED illuminates Red for Switch Fault	
Auto (LED)	Indicates OMS11 is in the Auto Mode	LED illuminates Green for Auto Mode	
Manual (LED)	Indicates the OMS11 is in the Manual Mode	LED illuminates Green for Manual Mode	
SELECT AUTO (Pushbutton)		Allows the operator to select Automatic Mode of operation	
ENABLE (Pushbutton)		Enables Front Panel controls to function	

## 3.1 Front Panel Interface

SELECT Modem A		Allows the operator to select		
(Pushbutton)		Modem A		
· /				
SELECT Modem B		Allows the operator to select		
(Pushbutton)		Modem B		
	Madam A Cantuala and Indi			
	Modem A Controls and Indi	cators		
Online LED	Indicates Modem A is	LED illuminates Green for Online		
	online			
Fault LED	The OMS11 has received	LED illuminates Red for Fault		
		LED IIIUIIIIIIales Keu IVI Fault		
	a fault from Modem A			
	Modem B Controls and Indi	oators		
Online LED	Indicates Modem B is	LED illuminates Green for Online		
	online			
Fault LED	The OMS11 has received	LED illuminates Red for Fault		
	a fault from Modem B			
Fault LED		LED illuminates Red for Fault		



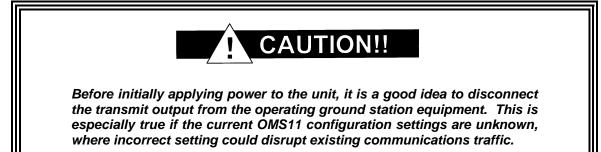
# Installation



## 4.0 Installation Requirements

The diagrams in this section display the OMS11 and OM20s mounted on the Antenna King Post as shown in figure 4-1 and 4-2. The cables supplied in the base system are based on this layout utilizing the mounting kit supplied by Radyne.







The OMS11 is shipped with protective covers over the connectors. The protective covers are used to create a moisture tight seal. Protective covers must remain on the unit if connector is not used.

## 4.1 Unpacking

The OMS11 was carefully packaged to avoid damage and should arrive complete with the following items for proper installation:

- OMS11 1:1 Redundancy Switch Unit
- Two AC or DC Mating connectors (J6 & J10)
- Data Mating Connector (J7)
- M&C Mating Connector (J8)
- OMS11/OM20 Interconnect Cables and Materials as required
- 1:1 Switch System Test Data Sheet
- An Installation and Operation Manual
- C-Band or Ku Band Waveguide Switches (Optional)
- Antenna Mounting hardware (Optional)
- BUCS and LNBS (Optional)

#### 4.1.1 Test Data Sheet

Each OMS11 1:1 Redundancy Switch system is shipped with a Test Data Sheet. This report contains information on the results of the Switch quality control testing. The report also includes information pertaining to the system settings that were made at the factory. Radyne recommends that the user save this report for future reference.

#### 4.2 Site Considerations

Adequate site planning and preparation simplifies the installation process and results in a more reliable system. The user should ensure that the site has adequate electrical power, environmental controls and protection against sources of electrical radiation and interference.

#### 4.2.1 Power Sources

The power sources should be properly grounded and as free as possible from electrical interference. The OMS11 employs a dual redundant power supply configuration. Each power connection on the OMS11 must be plugged into its own separate power circuit. Each circuit must have its own independent circuit breaker.

Grounding is achieved automatically when the properly terminated power connector is inserted into the power receptacle. This should be checked by testing that there is no voltage present between the chassis of the Switch and the power line ground.



The protective ground must not be bypassed or defeated In any way. Defeating the ground may result in operator Injury or damage to the system.



PROPER GROUNDING PROTECTION: During installation and setup, the user must ensure that the unit is properly grounded. The equipment shall be connected to the protective earth connection through the end use protective earth protection.



#### 4.3 System Setup & Connections

- 1. Install OMS11/OM20 Mounting kit as shown in Figure 4-1 and Table 4-1. This displays the optional Radyne unistrut mounting kit for antenna kingpost mounting.
- 2. Mount the units as shown per figure 4-2 below. Configure units. Note: Customer configurations may vary.
- 3. Install BUCs, LNBs and waveguide hardware onto mounting kit as shown in Figure 4-4. This displays the optional Radyne unistrut mounting kit for antenna kingpost mounting.
- 4. Attach the Power Cords to the OMS11 and OM20 units to be connected.
- 5. Power up the units to be connected. Their Green Power LEDs should illuminate. If not, refer to the appropriate Installation and Operation manual for further action to be taken.

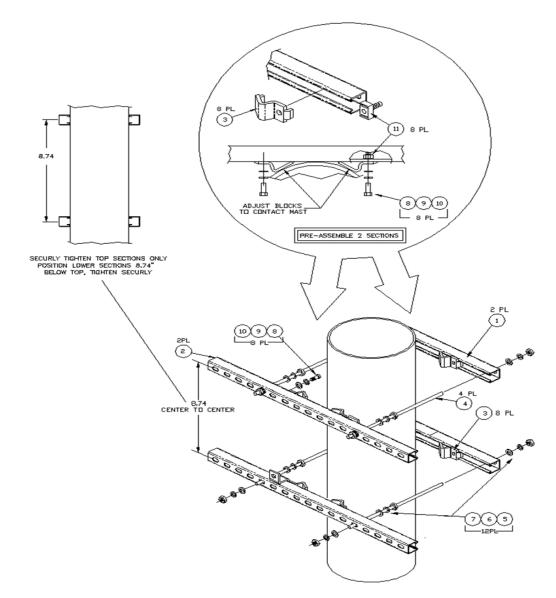


Figure 4-1 Antenna Mounting Kit
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Item	Radyne P/N	Description
1	FP5914-2	UNISTRUT 2 FEET
2	FP/5914-4	UNISTRUT 4 FEET
3	ZB356	PIPE BLOCK ELECTRO-PLATED FINISH
4	Z15ATC-04403	ALL THRD ROD 7/16-14 18.8 SS 3FT
5	Z15FNC3-044	NUT, 7/16-14, 18.8 S/S HEX
6	Z15LW3-044	LOCK WASHR 7/16 18.8 SS MEDIUM SPLT
7	Z15LW3-044	WASHER, 7/16, 18.8 S/S FLAT
8	Z15LW3-038	WASHER SPLIT LOCK 3/8 SS
9	Z15LW3-038	WASHER 3/8IN SS FLAT
10	Z15CSC3-0380125	BOLT HEXHD 3/8X1-1/4IN SS
11	ZN228WO	CHANNEL NUT 3/8-16 ELEC PLATE ZINC

#### Table 4-1 Antenna Mounting Kit

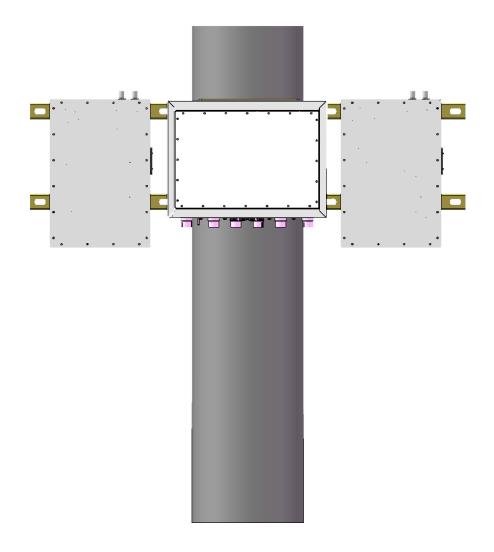


Figure 4-2 Antenna Mount Front View on King Post NOTE: All connections are facing down

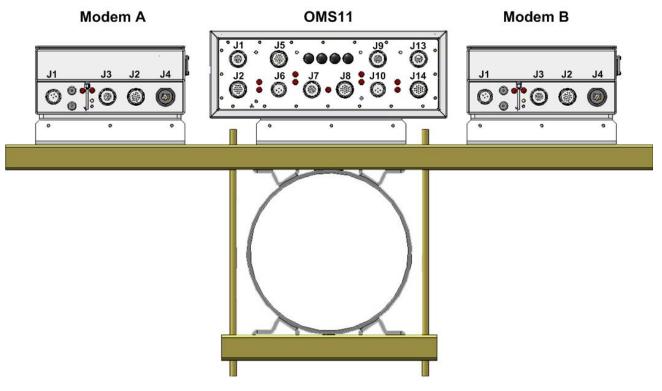


Figure 4-3 Antenna Mount Bottom View

Cable Connects	OMS11 Location	Modem A Location	Modem B Location	TX Waveguide	RX Waveguide	BUC A/B
CAR5902*	J1	J3				
CAR5902	J13		J3			
CAR5918**	J1	J3				
CAR5918**	J13		J3			
CAR5903	J2	J2				
CAR5903	J14		J2			
CAR5904	J5			J		
CAR5904	J9				J	
CAR5933		J3 Plug				J
CAR5933			J3 Plug			J

\* CAR5902 is for G703 Balanced Communications \*\* CAR5918 is for RS422 Serial Communications

Table 4-3 Cable Connections between OM20 and OMS11

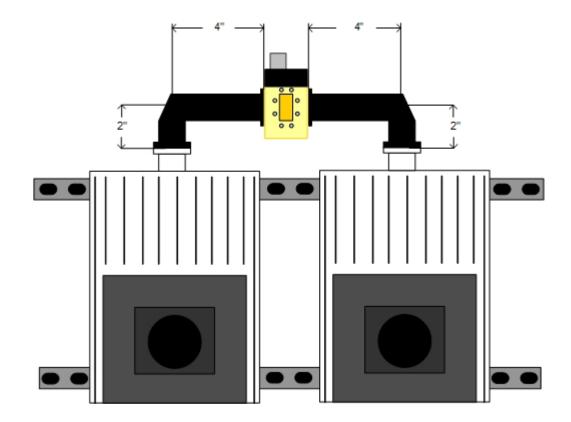


Figure 4-4 BUC Mount Front View on King Post NOTE: Reference only



# **Connector Pinouts**



#### 5.0 OMS11 External Interface Connections

All OMS11 external connections are interconnected to labeled connectors located on the front of the unit. Any connection interfacing to the OMS11 must utilize the appropriate mating connector (supplied). Refer to Table 5-1. OMS11 Connections and Figure 5-1. OMS11 Connection Ports for the standard unit. Reference throughout this section will be identified as the OMS11.

Table 5-1. OMS11 Connections				
Connector	Label	Description	Location	
J1	DATA A	RS422 Data I/O / G.703 Balanced / Async	MODEM A	
J2	M&C A	RS485 Monitor & Control	MODEM A	
J5	TX SW1	TX Waveguide I/O, 48V	OMS11	
J6	PWR 1	Power	OMS11	
J7	DATA	RS422 Data I/O / G.703 Balanced / Async	OMS11	
J8	M&C	RS232/RS485 Monitor & Control	OMS11	
J9	RX SW2	RX Waveguide I/O, 48V	OMS11	
J10	PWR 2	Power	OMS11	
J13	DATA B	RS422 Data I/O / G.703 Balanced / Async	MODEM B	
J14	M&C B	RS485 Monitor & Control	MODEM B	



Figure 5-1. OMS11 Connection Ports

## 5.1 LED Indicators

There are nine (9) Light Emitting Diodes (LED'S) on the front of the unit. LEDs identify status of Modem A, Modem B and OMS11. LEDs for Modem A and Modem B include Modems Online Status and Fault Status. LEDs for the OMS11 include Power 1 Status, Power 2 Status, OMS11 Fault status, Auto Mode and Manual Mode. When power is supplied to the unit and the power supply is functioning normally, this LED will be Green. Refer to Table 5-2. LED's for pin-out descriptions.

Table 5-2. LED's				
Label	Description	Location		
ONLINE	Modem online	MODEM A		
FAULT	Modem has a fault	MODEM A		
AUTO	Auto Mode selected	OMS11		
MANUAL	Manual Mode selected	OMS11		
FAULT	OMS 11 has a fault	OMS11		
PWR 1	Power 1 status	OMS11		
PWR 2	Power 2 status	OMS11		
ONLINE	Modem online	MODEM B		
FAULT	Modem has a fault	MODEM B		

#### 5.2 Power Input

## 5.2.1 AC Power Input (J6, J10)

AC Inputs are located on connector J6 and J10 of the OMS11. The auto-ranging universal power supply input allows for the connection of AC power to the port between the range of 100 - 240 VAC and 50 - 60 Hz. Power consumption for the unit is 1.0A (OMS11) only. An external chassis ground post is located on the OMS11. The ground post is a #10-32 threaded stud that is used for external grounding and should not be used to ground the AC power Source on J6 and J10. The mating power connector is a 4-pin socket MFG P/N (D38999/24FC4SN) connecter. The mating connector supplied with the unit.

Refer to Table 5-3 AC Powerfor the connector pinouts.

Table 5-3 AC Power		
А	Line (L1)	
В	Neutral (L2)	
С	Ground	

## 5.2.2 DC Power Input (J6, J10) (Optional)

An Optional DC Power Input is available for the OMS11. DC Inputs are located on connector J6 AND J10 of the OMS11. The unit may be powered from a 44 – 56 VDC source with maximum power consumption is 1.5 amps. This port is a 4-pin plug MFG P/N (D38999/24FC4PN) connector. The mating connector supplied with the unit. Refer to Table 5-4. DC Power for the connector pinouts.

Table 5-4. DC Power		
A	– VDC	
В	+ VDC	
С	Ground	
D	N/C	

## 5.3 Ground Lug

An external chassis ground post is located on the OMS11, which requires a #10-32 threaded stud.



## 5.4 Remote Monitor & Control (J8)

This port functions as the OMS11 Remote and Fault port utilizing an 18-Pin D38999/24FD18PN Connector. The Remote Port located on J8 allows for control and monitoring of parameters and functions via an RS-232 Serial Interface or RS-485 for RLLP Protocol. 'Equipment remote setup parameters can be configured via the main board or Terminal mode. Based on the user's application, this may require the user to set the Remote Port, properly configuring the units for Multidrop Address followed by setting the Remote Interface from RS232 to RS485.

The mating connector is supplied with the unit. Refer to Table 5-5 for the Remote/Terminal connector pinouts.

The OMS11's internal M&C system is connected to most of the circuitry on any board contained in the chassis. These connections provide status on the condition of the circuitry and provide the data required for the various measurements the OMS11 provides. The on-board M&C processes this information and generates status indications and alarms when necessary. Status information is available via the Remote port and the Form-C fault connections available on this connector. This summary information can be connected to external equipment or alarms. Refer to Table 5-3.

## 5.4.1 Terminal Mode (RS232)

The Terminal Mode has the advantage of providing full screen access to the switches parameters, but requires a separate terminal or computer running a Terminal Program. No external software is required other than VT-100 Terminal Emulation Software (e.g. "Procomm" for a computer when used as a terminal. The Control Port is normally used as an RS–232

Connection to the terminal device. This is the standard configuration when shipped from factory. Refer to Table 5-5for pinouts. Refer to Appendix A for configuring unit to RS232 Terminal.

The factory terminal setup is as follows:

Emulation Type:VT-100 (can be changed)Baud Rate:9600Data Bits:8Parity:No Parity (Fixed)Stop Bits:1 Stop Bit

The factory terminal Baud Rate can be changed by accessing dip switches located on the main board. Internal DIP switches are accessible only by removing the top cover. Refer to Appendix A, Figure A2.

# 5.4.2 Modem Remote Communications (RLLP/RS485)

The RLLP Remote Port is located on J8 allows for control and monitoring of parameters and functions via an RS-485. Control and status messages are conveyed between the modem and all subsidiary modems and the host computer using packetized message blocks in accordance with a proprietary communications specification. This communication is handled by the Radyne Link Level Protocol (RLLP), which serves as a protocol 'wrapper' for the RM&C data. Complete information on monitor and control software is contained in the following sections. Refer to Table 5-5 for pinout descriptions. Refer to Appendix A for configuring the unit to RS485 Remote. Refer to Appendix B for the RLLP Protocol.

This requires the user to first properly setup the unit ensuring Multidrop Address are configured as needed. The OMS11 has internal DIP switches that are accessible only by removing the top cover. DIP switch S3 is used to configure remote baud rates and addressing. Refer to Appendix A, Figure A2 for dip switch information. If you are having trouble with DIP switch settings, contact Radyne Customer Service for any additional help.

# 5.4.3 Common Equipment Faults (J8)

Common equipment fault hardware is available on the OMS11. The OMS11 M&C Connector (J8) has Form-C contacts available that indicate which modem is online and indicates OMS11 Fault status. Refer to Table 5-5.

Table 5.5. Remote Monitor & Control / Faults (J8)					
Pin No.	Signal Name	Signal	Direction		
А	Receive Data RS-232	RXD-232	Input		
В	Transmit Data RS-232	TXD-232	Output		
С	Reserved				
D	Transmit Data RS-485 (+)	TX-485-B	Output		
E	Transmit Data RS-485 (-)	TX-485-A	Output		
F	Receive Data RS-485 (+)	RX-485-B	Input		
G	Receive Data RS-485 (-)	RX-485-A	Input		

Н	Ground	GND	
J	Switch Fault – C	SF-C	
К	Switch Fault – NC	SF-NC	
L	Switch Fault – NO	SF-NO	
М	No Connect		
Ν	No Connect		
S	DSR		
R	No Connect		
U	No Connect		
Р	Modem A Online Relay – NC	MO-NC	
Т	Modem B Online Relay – NO	MO-NO	

## 5.4.3.1 Fault Detection

The OMS11 & OM20 work simultaneously to determine the status of all the components within this system. The OMS11 & OM20 are capable of monitoring BUC and LNB redundancy system. Faults detection is established by the OM20 and forwarded to the OMS11. Fault detection for a redundant BUC system will be different based on whether the BUC Power is supplied by the OM20 or if the BUC Power is supplied by an external power source. If the BUC power is supplied externally, then the BUC must have Normally Closed Form C Fault contacts so the OMS11/OM20 can monitor the BUC fault status.

Figure 5-2 reflects the BUC fault detection connector which is required for BUC that are using external Power supplies.



Figure 5-2 External BUC fault detection on CAR5902 or CAR5918

### Fault detection with the OM20 supplying power to BUC:

- BUC Faults OM20 uses internal fault detection circuitry to determine BUC status and initiates a fault that is forwarded to the OMS11
- OM20 uses internal fault detection circuitry to determine LNB status and initiate fault

### Fault detection with BUC power supplied externally:

- BUC must have Form C contacts in order for BUC fault detection to work
- OM20 data cable CAR5902 or CAR5918 has an external connector that is used to connect and monitor Form C Contacts from the BUC.
- OM20 uses internal fault detection circuitry to determine LNB status and initiate fault

## 5.5 Terrestrial Data Interface (J7) – RS422 Synchronous Data, Asynchronous Overhead Data, and G.703 Balanced Data I/O Port

This 37 Pin D38999/24FD35PN Connector contains the RS422 data connections, the RS485 Asynchronous Overhead data interface and the G.703 Balanced interface. Refer to Table 5-6 for pin-outs. Refer to Table 5-7 for G.703 Balanced pin-outs.

	Table 5.6. RS422 Synchronous Data I/O; Async Data Connector (J7)					
J7 Pin No.	Signal Name	Signal	Direction	EIA-530 25 Pin Connector Reference		
1	Shield			1		
2	Send Data B (+)	SD-B	Input	14		
3	Send Data A (-)	SD-A	Input	2		
4	Send Timing A (-)	ST-A	Output	15		
5	Receive Data	RD-A	Output	3		
6	Receive Data B (+)	RD-B	Output	16		
7	Request To Send A (-)	RS-A	Input	4		
8	Receive Timing A (-)	RT-A	Output	17		
9	Clear To Send A (-)	CS-A	Output	5		
10						
11	Data Mode A (-)	DM-A	Output	6		
12	Request To Send B (+)	RS-B	Input	19		
13	Signal Ground	SGND		7		
14	Data Terminal Ready A (-)	TR-A	Input	20		
15	Receiver Ready A (-)	RR-A	Output	8		
16						
17	Receive Timing B (+)	RT-B	Output	9		
18	Data Mode B (+)	DM-B	Output	22		
19	Receiver Ready B (+)	RR-B	Output	10		
20	Data Terminal Ready B (+)	TR-B	Input	23		
21	Terminal Timing B (+)	TT-B	Input	11		
22	Terminal Timing	TT-A	Input	14		
23	Send Timing B (+)	ST-B	Output	12		
24	No Connect			25		
25	Clear To Send B (+)	CS-B	Output	13		

Table 5.6 cont. RS422 Synchronous Data I/O; Async Data Connector (J7)				
J7 Pin No.	Async - Signal Name	Signal	Direction	
26	Transmit Data B (Async)	TXD_B	Input	N/C
27	Transmit Data A (Async)	TXD_A	Input	N/C
30	Receive Data A (Async)	RXD_A	Output	N/C
31	Receive Data B (Async)	RXD_B	Output	N/C

	Table 5.7. G.703 Balanced (J7)					
J7 Pin No.	G703 Balance - Signal Name	Signal	Direction	G.703 Balanced 15 Pin Connector Reference		
32	Send Data (-)	SD-A	Input	1		
35	Receive Data A (-)	RD-A	Output	3		
34	Ground	GND		4		
33	Send Data (+)	SD-B	Input	9		
36	Receive Data B (+)	RD-B	Output	11		
37						
29						
28						

## 5.6 Modem A Data Interface (J1) – RS422 Synchronous Data, Asynchronous Overhead Data, and G.703 Balanced Data I/O Port

This 37Pin D38999/24FD35PN Connector contains the RS422 data connections, RS485 Asynchronous Overhead data interface; G.703 Balanced interface, and the Open Collector Modulator and Demodulator Faults. Refer to Table 5-8 for pin-outs. Refer to Table 5-9 for G.703 Balanced.

	Table 5.8. RS422 Synchronous Data I/O; Async Data Connector (J1)					
J1 Pin No.	RS422 - Signal Name	Signal	Direction	EIA-530 Std. 25 Pin Reference		
1	Shield			1		
2	Send Data B (+)	SD-B	Input	14		
3	Send Data A (-)	SD-A	Input	2		
4	Send Timing A (-)	ST-A	Output	15		
5	Receive Data A (-)	RD-A	Output	3		
6	Receive Data B (+)	RD-B	Output	16		
7	Request To Send A (-)	RS-A	Input	4		
8	Receive Timing A (-)	RT-A	Output	17		
9	Clear To Send A (-)	CS-A	Output	5		
10	Modulator Fault – Open Collector	MF	Output	18		
11	Data Mode A (-)	DM-A	Output	6		
12	Request To Send B (+)	RS-B	Input	19		
13	Signal Ground	SGND		7		
14	Data Terminal Ready A (-)	TR-A	Input	20		
15	Receiver Ready A (-)	RR-A	Output	8		
16	Demodulator Fault	DF	Output	21		
17	Receive Timing B (+)	RT-B	Output	9		
18	Data Mode B (+)	DM-B	Output	22		
19	Receiver Ready B (+)	RR-B	Output	10		
20	Data Terminal Ready B (+)	TR-B	Input	23		
21	Terminal Timing B (+)	TT-B	Input	11		
22	Terminal Timing	TT-A	Input	14		
23	Send Timing B (+)	ST-B	Output	12		
24	No Connect			25		
25	Clear To Send B (+)	CS-B	Output	13		

NOTE: Data cables between the Modem and OMS11 are different based on interface type: G703 Balanced CAR5902

Table 5.8 cont. RS422 Synchronous Data I/O; Async Data Connector (J1)				
J1 Pin No.	Async - Signal Name	Signal	Direction	
26	Transmit Data B (Async)	TXD_B	Input	N/C
27	Transmit Data A (Async)	TXD_A	Input	N/C
28	No Connect			N/C
30	Receive Data A (Async)	RXD_A	Output	N/C
31	Receive Data B (Async)	RXD_B	Output	N/C

	Table 5.9 G.703 Balanced (J1)				
J1 Pin No.	G703 Balance - Signal Name	Signal	Direction	G.703 Balanced 15 Pin Reference	
32	Send Data (-)	SD-A	Input	1	
35	Receive Data A (-)	RD-A	Output	3	
34	Ground	GND		4	
33	Send Data (+)	SD-B	Input	9	
36	Receive Data B (+)	RD-B	Output	11	
37	No Connect			14	
29	No Connect			15	

## 5.7 Modem B Data Interface (J13) – RS422 Synchronous Data, Asynchronous Overhead Data, and G.703 Balanced Data I/O Port

This 38 Pin D38999/24FD35PN Connector contains the RS422 data connections, RS485 Asynchronous Overhead data interface; G.703 Balanced interface, and the Open Collector Modulator and Demodulator Faults. Refer to Table 5-10 for pin-outs. Refer to Table 5-11 for G.703 pin-outs.

RS422 CAR5918				
Та	able 5-10 RS422 Synchronous Data	I/O; Async D	ata Connecto	or (J13)
J13 Pin No.	RS422 - Signal Name	Signal	Direction	EIA-530 Std. 25 Pin Reference
1	Shield			1
2	Send Data B (+)	SD-B	Input	14
3	Send Data A (-)	SD-A	Input	2
4	Send Timing A (-)	ST-A	Output	15
5	Receive Data	RD-A	Output	3
6	Receive Data B (+)	RD-B	Output	16
7	Request To Send A (-)	RS-A	Input	4
8	Receive Timing A (-)	RT-A	Output	17
9	Clear To Send A (-)	CS-A	Output	5
10	Modulator Fault – Open Collector	MF	Output	18
11	Data Mode A (-)	DM-A	Output	6
12	Request To Send B (+)	RS-B	Input	19
13	Signal Ground	SGND		7
14	Data Terminal Ready A (-)	TR-A	Input	20
15	Receiver Ready A (-)	RR-A	Output	8
16	Demodulator Fault	DF	Output	21
17	Receive Timing B (+)	RT-B	Output	9
18	Data Mode B (+)	DM-B	Output	22
19	Receiver Ready B (+)	RR-B	Output	10
20	Data Terminal Ready B (+)	TR-B	Input	23
21	Terminal Timing B (+)	TT-B	Input	11
22	Terminal Timing	TT-A	Input	14
23	Send Timing B (+)	ST-B	Output	12
24	No Connect			25
25	Clear To Send B (+)	CS-B	Output	13

NOTE:	Data cables between th	e Modem and OMS11 are different based on interface type:
	G703 Balanced	CAR5902
	DC100	CAR5018

Table 5-10 cont. RS422 Synchronous Data I/O; Async Data Connector (J13)				
J13 Pin No.	Async - Signal Name	Signal	Direction	
26	Transmit Data B (Async)	TXD_B	Input	N/C
27	Transmit Data A (Async)	TXD_A	Input	N/C
28	No Connect			N/C
30	Receive Data A (Async)	RXD_A	Output	N/C
31	Receive Data B (Async)	RXD_B	Output	N/C

	Table 5-11 G.703 Balanced (J13)				
J13 Pin No.	G703 Balance - Signal Name	Signal	Direction	G.703 Bal 15 Pin Connector Reference	
32	Send Data (-)	SD-A	Input	1	
35	Receive Data A (-)	RD-A	Output	3	
34	Ground	GND		4	
33	Send Data (+)	SD-B	Input	9	
36	Receive Data B (+)	RD-B	Output	11	
37	No Connect			14	
29	No Connect			15	

# 5.8 Modem A Remote/Terminal/Fault Port on OMS11 (J2)

This port provides Fault status and RS485 Communications to the OMS11 from the OM20 (Modem A). This port utilizes an 18-Pin D38999/24FD18PN Connector. Refer to Table 5-12 for the pinout information.

Table 5-12 Remote/Terminal/Fault Connector (J2)					
Pin No.	Signal Name	Signal	Direction		
А	Receive Data RS-232	RX-232			
В	Transmit Data RS-232	TX-232			
С	No Connect				
D	Transmit Data RS-485 (+)	TX-485-B	Output		
E	Transmit Data RS-485 (-)	TX-485-A	Output		
F	Receive Data RS-485 (+)	RX-485-B	Input		
G	Receive Data RS-485 (-)	Input			
н	Ground	GND			
J	Mod Fault – Common	MF-C			
К	Mod Fault – NC	MF-NC			
L	Mod Fault – NO	MF-NO			
М	Demod Fault - Common	DF-C			
N	Demod Fault – NO	DF-NO			
S	Demod Fault – NC	d Fault – NC DF-NC			
R	Ground GND				
U	No Connect				
Р	No Connect				
Т	No Connect				

# 5.9 Modem B Remote/Terminal/Fault Port on the OMS11 (J14)

This port provides Fault status and RS485 Communications to the OMS11 from the OM20 (Modem B). This port utilizes an 18-Pin D38999/24FD18PN Connector. Refer to Table 5-13 for the pinout information.

Table 5-13 Remote/Terminal/Fault Connector (J14)					
Pin No.	Signal Name	Signal	Direction		
А	Receive Data RS-232	RX-232			
В	Transmit Data RS-232	TX-232			
С	No Connect				
D	Transmit Data RS-485 (+)	TX-485-B	Output		
E	Transmit Data RS-485 (-)	TX-485-A	Output		
F	Receive Data RS-485 (+)	RX-485-B	Input		
G	Receive Data RS-485 (-)	RX-485-A	Input		
Н	Ground	GND			
J	Mod Fault – Common MF-C				
К	Mod Fault – NC MF-NC				
L	Mod Fault – NO	MF-NO			
М	Demod Fault - Common DF-C				
N	Demod Fault – NO	DF-NO			
S	Demod Fault – NC DF-NC				
R	Ground	GND			
U	No Connect				
Р	No Connect				
Т	No Connect				

# 5.10 TX & RX Waveguide Switch Interface (J5 & J9)

These ports provide 48Volts for switching the RX and TX Waveguide switches. For TX waveguide switching, connect the CAR5904 cable between the J5 of the OMS11 to the TX waveguide Switch. For RX waveguide switching, connect the CAR5904 cable between the J9 of the OMS11. The chart below identifies the J5 & J9 pinouts on the OMS11 and the mating connector pinout for a Sector Microwave Switch. Connector information and pinout descriptions are identified below. Refer to Table 5-14 and Figure 5-3. CAR5904 is supplied by Radyne when waveguide switching hardware is supplied by Radyne.

Table 5-15	Table 5-154 CAR5904 OMS11 TO SECTOR MICROWAVE W/G SWITCH					
SECTOR MICROWAVE SWITCH						
CONNECTOR	OMS11 J5 / J9	TX / RX W/G SW				
MFGR	AMPHENOL	SOUR				
HOUSING AL07F15-18		MS3116F12-10S				
DESCRIPTION JAM NUT RECPT		CONN. W/ST.RELF.				
CONTACTS	10-251415-205	INC.				
STRAIN RELIEF	M85049-38S15N	INC.				
	MFG: NATIONAL					
CABLE INFO	CABLE	P/N: NQP-1928SJ				

WIRING LIST							
SIGNAL CONN # PIN # CONN # PIN #							
N/C	N/C	N/C					
Common	В	В					
Pos 2 Volts	С	С					
Pos 1, Ind 1	D	D					
Pos 1 Common	E	E					
Pos 2, Ind 1,	F	F					
Pos 1, Ind 2	G	G					
Ind 2, Com	Н	Н					
Pos 2, Ind 2	J	J					
N/C	K	N/C					
N/C	L	N/C					
N/C	М	N/C					
N/C	Ν	N/C					
N/C	S	N/C					
N/C	R	N/C					
N/C	U	N/C					
N/C	Р	N/C					
Pos 1 Volts	Т	A					

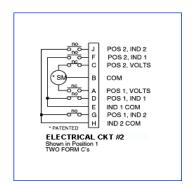


Figure 5-3. Pinout for Sector Microwave Switch

## 5.11 Mating Connectors

The chart below identifies Radyne and Manufacturer part numbers for the mating connectors to the OMS11. Refer to Table 5-15 for connector part numbers.

Table 5-15 Mating Connectors					
Connector	Description	Radyne P/N	MFG P/N Amphenol		
J1 & J13	Data	CN/26FD35SN	JD3899/26FD35SN		
J1 & J13	Data / Stress Relief	CN/M85049/38-15	M85049/3/-15A		
J2 & J14	Faults	CN/26FD18SN	JD38999/26FD18SN		
J2 & J14	Faults / Stress Relief	CN/M85049/38-15	M85049/38-15A		
J5 & J9	TX/RX WG SW	CN/26FD18SN	JD38999/26FD18SN		
J5 & J9	TX/RX WG SW / Stress Relief	CN/M85049/38 -15	M85049/38-15A		
J6 & J10	Power / DC	CN/26FC4PN	D38999/26FC4PN		
J6 & J10	Power / DC / Stress Relief	CN/M85049/38-13	M85049/38-13A		
J6 & J10	Power / AC	CN/26FC4SN	D38999/26FC4SN		
J6 & J10	Power / AC / Stress Relief	CN/M85049/38-13	M85049/38-13A		
J7	Data	CN/26FD35SN	JD3899/26FD35SN		
J7	Data / Stress Relief	CN/M85049/38-15	M85049/3/-15A		
J8	Faults	CN/26FD18SN	JD38999/26FD18SN		
J8	Faults / Stress Relief	CN/M85049/38-15	M85049/38-15A		



# Maintenance and Troubleshooting



## 6.0 Basic Troubleshooting and Maintenance

This section provides information on the basic troubleshooting and repair procedures for the OMS11 1:1 Switch that may be performed on-site by qualified personnel. Only minor repairs will be discussed. For serious failures, the user should not attempt to repair the unit without first contacting the Radyne Customer Service Department at 602-437-9620 for further information and instructions.

### 6.1 Basic User Checks

Upon the detection of an operational failure, the source of the failure must be determined. Basic user checks include checking the various cables and connectors.

## 6.1.1 Checking the Cabling and Connectors

Problems that appear difficult to solve can often be traced to a loose or defective cable or connector. The user should first verify the following:

- All cables within the system have no broken or loose connections. Cables that are suspect should be replaced.
- All jacks on the units have no bent or broken pins.
- Both AC Power Cords are properly plugged into the rear of the OMS11.

### 6.2 Major and Minor Faults

Major faults are failure conditions or combinations of conditions that result in loss of service on one or more channels. Minor faults are failure conditions that do not result in loss of service.

Possible Major Fault conditions are:

- A Read-Only Memory (ROM) failure in the Switch;
- A Random Access Memory (RAM) failure in the Switch;
- A loss of Carrier Detect on a Demodulator Channel where this attribute is monitored;
- A loss of Terrestrial Input Clock on a Channel where this attribute is monitored;
- A failure of two monitored Modulators;
- A failure of two monitored Demodulators;
- A failure of both OMS11 power supplies.

Possible Minor Fault conditions are as follows:

- A failure of one of the Switch's two redundant power supplies;
- A failure of one Demodulator that is being monitored (i.e., a Demodulator that has not been locked out);
- A failure of one Modulator that is being monitored;
- A reference clock slip.



# **Technical Specifications**



## 7.0 Introduction

This section defines the technical performance parameters and specifications for the OMS11 1:1 Redundancy Switch.

### 7.1 General

Modes of Operation: Configurations: Modem Switch Time: Auto, Manual, Remote Modem (Chain Switch) 50 msec Maximum

## 7.2 Monitor and Control

Operating parameters can be monitored and controlled via the RS232 Terminal port or the RS485 RLLP control channel. The following modem parameters may be controlled and/or monitored:

Parameters Monitored:

Mode, Modem, Power Supply Status, Internal Switch Settings, Software Revision, Auto/Manual, Select A, Select B Modem, Auto/Manual, Select A, Select B

Parameters Controlled:

## 7.3 Terrestrial Interfaces

RS422 & G703 Balanced RS422 & G703 Unbalanced (Optional)

## 7.4 Modem Data Cables

CAR5902	G703 Balanced
CAR5918	RS422

## 7.5 Front Panel LED Indicators

Unit:	Power Supply 1
	Power Supply 2
	Switch Fault
	Auto
	Manual
Modem:	Online A
	Online B
	Fault A
	Fault B

## 7.6 Front Panel Controls

Enable Select Auto Modem Select A Modem Select B

## 7.7 **Power and Environmental**

Prime Power:	100 to 240VAC, 50/60 Hz, 40W typ, 200W Max 44 - 56VDC, 40W typical, 200W Max during switchover			
Operating Temperature:	-40 to 50°C, 95% Humidity, Noncondensing			

Operating Temperature:	-40 to 50°C, 95% Humidity, Noncondensing
Storage Temperature:	-50 to 70°C, 99% Humidity, Noncondensing

# 7.8 Physical

OMS11	Chassis Size:
-------	---------------

11.4" L x 15.4" W x 5.7" H (28.9 cm x 39.1 cm x 14.48 cm) 12 Pounds (5.4 Kg)



# **OMS11 DIP Switch Configuration**



The OMS11 has four internal DIP switches that are accessible only by removing the top cover. These DIP switches S2, S3, S4 & S5 are used to configure Interface options, data rates and remote baud rates. An upgrade or change from an existing interface or configuration to another may require a change to one or more of the DIP switch settings. If you are having trouble with DIP switch settings, contact Radyne Customer Service for any additional help.

Figure A-1 Illustrates the DIP switch positions for the OM20.

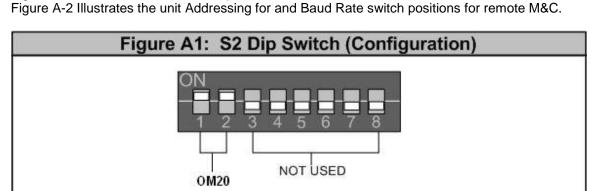
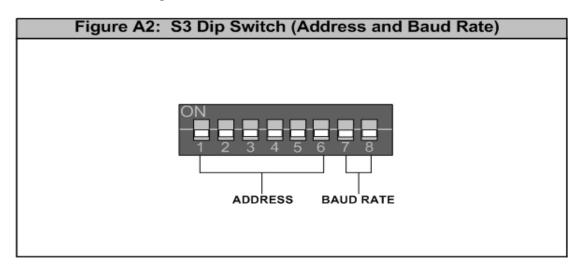


Figure A-1. DIP Switch Positions for the OM20



### Figure A2. DIP Switch showing Address and Baud Rate

Table A-1 identifies the various S3 dip switch positions. Pins 1 - 6 are utilized for M&C unit addressing when using multiple switches. Pins 7 & 8 are utilized for baud rate for the terminal or remote M&C. Address settings are also accessible through the Remote Port (J-20) with the switch in Terminal Mode. An empty space in Table A-1: represents the (off) position.

Table A-1. Baud Rate Switch Positions								
BAUD RATE	SW-1	SW-2	SW-3	SW-4	SW-5	SW-6	SW-7	SW-8
9600								
4800							ON	
2400								ON
ADDRESS								
32								
33 34	ON	ON						
35	ON	ON						
36	ON	ON	ON					
37	ON		ON					
38	0.1	ON	ON					
39	ON	ON	ON					
40				ON				
41	ON			ON				
42		ON		ON				
43	ON	ON		ON				
44			ON	ON				
45	ON		ON	ON				
46		ON	ON	ON				
47	ON	ON	ON	ON				
48					ON			
49	ON				ON			
50		ON			ON			
51	ON	ON			ON			
52	ON		ON		ON			
53	ON		ON		ON			
54 55	ON	ON ON	ON ON		ON ON			
56	ON	UN	ON	ON	ON			
57	ON			ON	ON			
58	ON	ON		ON	ON			
59	ON	ON		ON	ON			
60			ON	ON	ON			
61	ON		ON	ON	ON			
62	<u>on</u>	ON	ON	ON	ON			
63	ON	ON	ON	ON	ON			
64	_		-	-	-	ON		
65	ON					ON		
66		ON				ON		
67	ON	ON				ON		
68			ON			ON		
69	ON		ON			ON		
70		ON	ON			ON		
71	ON	ON	ON			ON		
72				ON		ON		
73	ON	L		ON		ON		
74		ON		ON		ON	ļ	
75	ON	ON		ON		ON		
76			ON	ON		ON		
77	ON		ON	ON		ON		
78		ON	ON ON	ON		ON		
79 80	ON	ON	UN	ON	ON	ON ON		
80	ON	<u> </u>			ON	ON		
82		ON			ON	ON		
83	ON	ON			ON	ON		
84	0.1		ON		ON	ON		1
85	ON	1	ON		ON	ON		1
86		ON	ON		ON	ON		
87	ON	ON	ON	1	ON	ON	1	1
88	1	1		ON	ON	ON	1	1
89	ON	1	1	ON	ON	ON	1	1
90	1	ON	1	ON	ON	ON	1	1
91	ON	ON	İ	ON	ON	ON		1
92			ON	ON	ON	ON		
93	ON		ON	ON	ON	ON		
94		ON	ON	ON	ON	ON		
SOFT	ON	ON	ON	ON	ON	ON		



Figure A3 Illustrates how to configure the Dip Switches for RS232 Data on an OMS11.

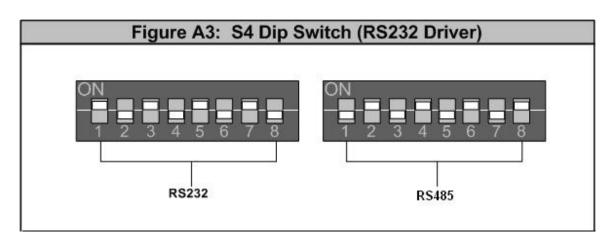


Figure A3. DIP Switch on the RS232 Driver

Figure A4 Illustrates how to configure the Dip Switches for G.703 Unbalanced data on an OMS11 with Universal Data Interface.

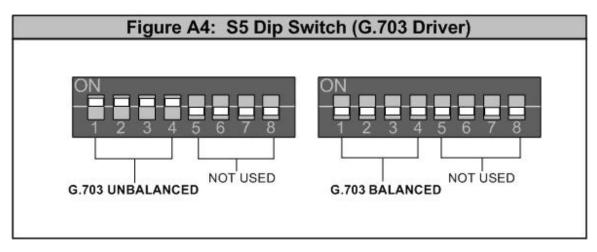


Figure A4. DIP Switch on the G.703 Driver

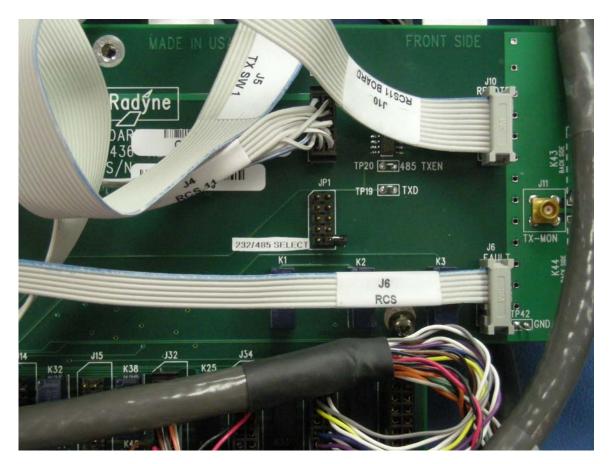


Figure A5. JP1 on AS/3436-6

Figure A5 illustrates the standard jumper block for configuring unit to RS485 Remote or RS232 Terminal mode. Unit is configured to RS232 Terminal when shipped from the factory as per the picture above.

The diagram above indicates an RS232 configuration. Installing the jumper, connecting the pins will configure the unit for RS485.



# **OMS11** Remote Communications



## **B.0** Host Computer Remote Communications

Control and status messages are conveyed between the OMS11 and the host computer using packetized message blocks in accordance with a proprietary communications specification. This communication is handled by the Radyne Link Level Protocol (RLLP), which serves as a protocol 'wrapper' for the RM&C data.

Complete information on monitor and control software is contained in the Radyne RLLP Protocol Reference Guide.

	DTE
For RS485 Remote communication, ins the remote port. Gender changes port f	

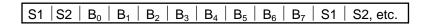
## **B.0.1** Protocol Structure

The Communications Specification (COMMSPEC) defines the interaction of computer resident Monitor and Control software used in satellite earth station equipment such as Modems, redundancy switches, multiplexers, and other ancillary support gear. Communication is bidirectional, and is normally established on one or more full-duplex 9600-baud multi-drop control buses that conform to EIA Standard RS-485.

Each piece of earth station equipment on a control bus has a unique physical address, which is assigned during station setup/configuration or prior to shipment. Valid decimal addresses on one control bus range from 032 through 255 for a total of up to 224 devices per bus. Address 255 of each control bus is usually reserved for the M&C computer.

## **B.0.2 Protocol Wrapper**

The Radyne COMMSPEC is byte-oriented, with the Least Significant Bit (LSB) issued first. Each data byte is conveyed as mark/space information with two marks comprising the stop data. When the last byte of data is transmitted, a hold comprises one steady mark (the last stop bit). To begin or resume data transfer, a space (00h) substitutes this mark. This handling scheme is controlled by the hardware and is transparent to the user. A pictorial representation of the data and its surrounding overhead may be shown as follows:



The stop bits, S1 and S2, are each a mark. Data flow remains in a hold mode until S2 is replaced by a space. If S2 is followed by a space, it is considered a start bit for the data byte and not part of the actual data ( $B_0$  -  $B_7$ ).

The COMMSPEC developed for use with the Radyne Link Level Protocol (RLLP) organizes the actual monitor and control data within a shell, or 'protocol wrapper', which surrounds the data. The format and structure of the COMMSPEC message exchanges are described herein. Decimal numbers have no suffix; hexadecimal numbers end with a lower case h suffix and binary values have a lower case b suffix. Thus, 22 = 16h = 000010110b. The principal elements of a data frame, in order of occurrence, are summarized as follows:

**<SYN>** - the message format header character, or ASCII sync character, that defines the beginning of a message. The <SYN> character value is always 16h.

**<DATA COUNT>** - the 2 Byte Data Count is the number of bytes in the <DATA> field, ranging from 0 through 509.

**SOURCE ID>** - the Source Identifier defines the multi-drop address origin. Note that all nodes on a given control bus has an unique address that must be defined.

**<DESTINATION ID>** - the Destination Identifier serves as a pointer to the multi-drop destination device that indicates where the message is to be sent.

**FRAME SEQUENCE NUMBER>** -the FSN is a tag with a value from O through 255 that is sent with each message. It assures sequential information framing and correct equipment acknowledgment and data transfers.

**<OPCODE>** - the 2 Byte Operation Code field contains a number that identifies the message type associated with the data that follows it. Equipment under MCS control recognizes this byte via firmware identification and subsequently steers the DATA accordingly to perform a specific function or series of functions. Acknowledgment and error codes are returned in this field. 1 Byte for the DMD5000 protocol and 2 Bytes for the DMD15 protocol.

**COPCODE** - the Data field contains the binary, bi-directional data bytes associated with the COPCODE> - The number of data bytes in this field is indicated by the <BYTE COUNT> value.

<CHECKSUM> - the checksum is the modulo 256 sum of all preceding message bytes, excluding the <SYN> character. The checksum determines the presence or absence of errors within the message. In a message block with the following parameters, the checksum is computed as shown in Table 1.

BYTE FIELD	DATA	<u>CONTENT</u>	RUNNING CHECKSUM
<byte count=""> <byte count=""> <sourceid> <destination id=""> <fsn> <opcode> <data> (Byte 1) <data> (Byte 2)</data></data></opcode></fsn></destination></sourceid></byte></byte>	02h 02h F0h 2Ah 09h 03h DFh FEh	= 0000000b = 0000010b = 11110000b = 00101010b = 00001001b = 11011111b = 11111110b	00000000b 00000010b 11110010b 00011100b 00100101b 00101000b 00000111b 00000101b

#### Table 1. Checksum Calculation Example

Thus, the checksum is 00000101b; which is 05h or 5 decimal. Alternative methods of calculating the checksum for the same message frame are:

02h + FOh + 2Ah + 09h + 03h + DFh + FEh = 305h.

Since the only concern is the modulo 256 (modulo 1 00h) equivalent (values that can be represented by a single 8-bit byte), the checksum is 05h.

For a decimal checksum calculation, the equivalent values for each information field are: 0 + 2 + 240 + 42 + 9 + 3 + 223 + 254 = 773; 773/256 = 3 with a remainder of 5.

This remainder is the checksum for the frame. 5 (decimal) = 05h = 0101b = <CHECKSUM> ]

## **B.0.3 Frame Description and Bus Handshaking**

In a Monitor and Control environment, every message frame on a control bus port executes as a packet in a loop beginning with a wait-for-SYN-character mode. The remaining message format header information is then loaded, either by the M&C computer or by a subordinate piece of equipment (such as the DMD15) requesting access to the bus. Data is processed in accordance with the OPCODE, and the checksum for the frame is calculated.

If the anticipated checksum does not match then a checksum error response is returned to the message frame originator. The entire message frame is discarded and the wait-for-SYN mode goes back into effect. If the OPCODE resides within a command message, it defines the class of action that denotes an instruction which is specific to the device type, and is a prefix to the DATA field if data is required. If the OPCODE resides within a query message packet, then it defines the query code, and can serve as a prefix to query code DATA.

The Frame Sequence Number (FSN) is included in every message packet and increments sequentially. When the M & C computer or bus-linked equipment initiates a message, it assigns the FSN as a tag for error control and handshaking. A different FSN is produced for each new message from the FSN originator to a specific device on the control bus. If a command packet is sent and not received at its intended destination, then an appropriate response message is not received by the packet originator. The original command packet is then re-transmitted with the same FSN. If the repeated message is received correctly at this point, it is considered a new message and is executed and acknowledged as such.

If the command packet is received at its intended destination but the response message (acknowledgment) is lost, then the message originator (usually the M&C computer) re-transmits the original command packet with the same FSN. The destination device detects the same FSN and recognizes that the message is a duplicate, so the associated commands within the packet are not executed a second time. However, the response packet is again sent back to the source as an acknowledgment in order to preclude undesired multiple executions of the same command.

To reiterate, valid equipment responses to a message require the FSN tag in the command packet. These serve as part of the handshake/acknowledge routine. If a valid response message is absent, then the command is re-transmitted with the same FSN. For a repeat of the same command involving iterative processes (such as increasing or decreasing the transmit power level of a DMD15 modulator), the FSN is incremented after each message packet. When the FSN value reaches 255, it overflows and begins again at zero. The FSN tag is a powerful tool that assures sequential information framing, and is especially useful where commands require more than one message packet.

The full handshake/acknowledgment involves a reversal of source and destination ID codes in the next message frame, followed by a response code in the <OPCODE> field of the message packet from the equipment under control.

If a command packet is sent and not received at its intended destination, a timeout condition can occur because a response message is not received by the packet originator. On receiving devices slaved to an M & C computer, the timeout delay parameters may be programmed into the equipment in accordance with site requirements by Radyne Corp. prior to shipment, or altered by qualified personnel. The FSN handshake routines must account for timeout delays and be able to introduce them as well.

## **B.0.4 Global Response Operational Codes**

In acknowledgment (response) packets, the operational code <OPCODE> field of the message packet is set to 0 by the receiving devices when the message intended for the device is evaluated as valid. The device that receives the valid message then exchanges the <SOURCE ID> with the <DESTINATION ID>, sets the <OPCODE> to zero in order to indicate that a good message was received, and returns the packet to the originator.

This "GOOD MESSAGE" opcode is one of nine global responses. Global response opcodes are common responses, issued to the M&C computer or to another device that can originate from and are interpreted by all Radyne equipment in the same manner. These are summarized as follows (all opcode values are expressed in decimal form):

RESPONSE OPCODE DESCRIPTION	OPCODE
Good Message	000
Bad Parameter	255
Bad Opcode	254
Bad Checksum	253
Command Not Allowed in LOCAL Mode	252
Command Not Allowed in AUTO Mode Bad Destination	252 251 250
Unable to Process Command	249
Packet Too Long	248

### Table 2. Response OPCODES

## **B.0.5 Software Compatibility**



The COMMSPEC, operating in conjunction within the RLLP shell, provides for full forward and backward software compatibility independent of the software version in use. New features are appended to the end of the DATA field without OPCODE changes. Older software simply discards the data as extraneous information without functional impairment for backward compatibility.

If new device-resident or M&C software receives a message related to an old software version, new information and processes are not damaged or affected by the omission of data.

The implementation of forward and backward software compatibility often, but not always, requires the addition of new Opcodes. Each new function requires a new Opcode assignment if forward and backward compatibility cannot be attained by other means.

## B.0.6 RLLP Summary

The RLLP is a simple send-and-wait protocol that automatically re-transmits a packet whenever an error is detected, or when an acknowledgment (response) packet is absent.

During transmission, the protocol wrapper surrounds the actual data to form information packets. Each transmitted packet is subject to time out and frame sequence control parameters, after which the packet sender waits for the receiver to convey its response. Once a receiver verifies that a packet sent to it is in the correct sequence relative to the previously received packet, it computes a local checksum on all information within the packet excluding the <SYN> character and the <CHECKSUM> fields. If this checksum matches the packet <CHECKSUM>, the receiver processes the packet and responds to the packet sender with a valid response (acknowledgment) packet. If the checksum values do not match, the receiver replies with a negative acknowledgment (NAK) in its response frame.

The response packet is therefore either an acknowledgment that the message was received correctly, or some form of a packetized NAK frame. If the sender receives a valid acknowledgment (response) packet from the receiver, the <FSN> increments and the next packet is transmitted as required by the sender. However, if a NAK response packet is returned the sender re-transmits the original information packet with the same embedded <FSN>.

If an acknowledgment (response) packet or a NAK packet is lost, corrupted, or not issued due to an error and is thereby not returned to the sender, the sender re-transmits the original information packet; but with the same <FSN>. When the intended receiver detects a duplicate packet, the packet is acknowledged with a response packet and internally discarded to preclude undesired repetitive executions. If the M&C computer sends a command packet and the corresponding response packet is lost due to a system or internal error, the computer times out and re-transmits the same command packet with the same <FSN> to the same receiver and waits once again for an acknowledgment or a NAK packet.

To reiterate, the format of the message block is shown in below in Table 3, Link Level Protocol Message Block.

	SYNC	COUNT	SRC ADDR	DEST ADDR	FSN	OP CODE	DATA BYTES	CHECKSUM
--	------	-------	----------	-----------	-----	---------	------------	----------

### Table 3. Link Level Protocol Message Block

### B.1 Remote Port Packet Structure:

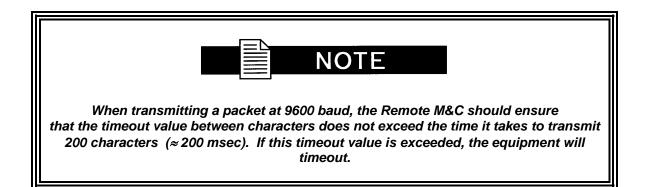
The OMS11 protocol is an enhancement on the DMD5000 protocol. It also uses a packet structure format. The structure is as follows:

<sync></sync>	=	Message format header character that defines the beginning of a message. The <sync> character value is</sync>
always 0x16. (1 byte)		
<byte count=""></byte>	=	Number of bytes in the <data> field. (2 bytes)</data>
<source id=""/>	=	Identifies the address of the equipment from where the message originated. (1 byte)
<dest. id=""> be</dest.>	=	Identifies the address of the equipment where the message is to sent. (1 byte)
<f.s.n.> acknowledgment and</f.s.n.>	=	Frame sequence number insures correct packet data transfers. (1 byte)

<opcode></opcode>	=	This byte identifies the message type associated with the
		information data. The equipment processes the
data according to		the value in this field. Return
error codes and ackno this field. (2 bytes)	owledgme	ent are also included in
<data></data>	=	Information data. The number of data bytes in this field is
indicated		by the <byte count=""> value.</byte>
<checksum> the</checksum>	=	The modulo 256 sum of all preceding message bytes excluding <sync> character. (1 byte)</sync>

**CAUTION!!** 

The DMD15 RLLP is not software-compatible with the following previous Radyne products: RCU5000 and DMD4500. These products may not occupy the same bus while using this protocol as equipment malfunction and loss of data may occur.



#### **Regular Commands**

#### Opcode <2000h> Query OMS11 Device Identification

Query Response Data Field (1 byte): <1> Device Identification 26

26 decimal for OMS11

null terminated string

null terminated string

0x55

0xAA

binary number, implied decimal point

binary number, implied decimal point

#### Opcode <2080h> Query OMS11 Device Firmware Version

Query Response Data Field (19 bytes):

- <1> Device Firmware Version MSB
- <1> Device Firmware Version LSB
- <10> Device Firmware Name
- <7> Device Firmware Release Date

Opcode <2280h> Command OMS11 Load Factory Defaults

Command Data Field (2 bytes):

- <1> Unlock Code 1
- <1> Unlock Code 2

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Opcode <2083h> Query OMS11 Backup Configuration Query Response Data Field (1 byte):				
<1>	Backup Configuration	0 = Modem (Coupled)		
		1 = Mod Only		
		2 = Demod Only		
		3 = Mod/Demod (Uncoupled)		
	le <2084h> Query OMS11 Backup Response Data Field (1 byte):	o Mode		
<1>	Backup Mode	0 = Manual		
		1 = Automatic		
		$2 = \langle unknown \rangle$		
_				
Comm	le <2284h> Command OMS11 Ba and Data Field (1 byte):	ckup Mode		
<1>	Backup Mode	0 = Manual		
		1 = Automatic		
Opcod	le <2085h>   Query OMS11 Backup	State		
	Response Data Field (2 bytes):			
<1>	Mod Backup state	0 = A online		
		1 = B online		
		2 = <none or="" unknown=""></none>		
<1>	Demod Backup State	0 = A online		
		1 = B Online		
		2 = <none or="" unknown=""></none>		
Oncor	le <2285h> Command OMS11 Fo	ree Manual Backun		
	and Data Field (2 bytes):	ice Manual Backup		
<1>	Mod Backup State	0 = A online		
	·	1 = B online		
<1>	Demod Backup State	0 = A  online		
		1 = B online		
Opcoc	le <2086h> Query OMS11 Switch	Delavs		
	Response Data Field (8 Bytes):			
<1>	Switch Delay Mod Fault MSB			
<1>				
<1>	1> Switch Delay Mod NoFault MSB			
<1>	Switch Delay Mod NoFault LSB			
<1>	Switch Delay Demod Fault MSB			
<1>	Switch Delay Demod Fault LSB			

- <1> Switch Delay Demod NoFault MSB
- <1> Switch Delay Demod NoFault LSB

#### Opcode <2286h> Command OMS11 Switch Delays

Command Data Field (8 Bytes):

- <1> Switch Delay Mod Fault MSB
- <1> Switch Delay Mod Fault LSB
- <1> Switch Delay Mod NoFault MSB
- <1> Switch Delay Mod NoFault LSB
- <1> Switch Delay Demod Fault MSB
- <1> Switch Delay Demod Fault LSB
- <1> Switch Delay Demod NoFault MSB

### <1> Switch Delay Demod NoFault LSB

#### Opcode <2087h> Query OMS11 Switch Alarms

Query I	Response Data Field (5 bytes):	
<1>	Global Current Alarm	Bit 0: 1 = Global Alarm
		Bit 1:.7: unused, return 0
<1>	External Current Alarms	
		Bit 0: 1 = Mod A Alarm
		Bit 1: 1 = Force Mod A Alarm
		Bit 2: 1 = Demod A Alarm
		Bit 3: 1 = Force Demod A Alarm
		Bit 4: 1 = Mod B Alarm
		Bit 5: 1 = Force Mod B Alarm
		Bit 6: 1 = Demod B Alarm
		Bit 7: 1 = Force Demod B Alarm
<1>	Switch Current Alarms	
		Bit 0: 1 = Switch Power 1 Alarm
		Bit 1: 1 = Switch Power 2 Alarm
		Bit 2: 1 = Switch Firmware Alarm
		Bit 3: 1 = Switch NV Alarm
		Bit 4: 1 = Switch Internal Alarm
		Bit 5:.7: unused, return 0
<2>	Spare Current Alarms	Always 0

## Opcode: <2089h> Query OMS11 Switch Alarms Mask

Query	Response Data Field (4 Bytes):	
<1>	External Alarm Masks	1 = Enabled, 0 = Masked Off Bit 0: 1 = Mod A Alarm Enabled Bit 1: 1 = Force Mod A Alarm Enabled Bit 2: 1 = Demod A Alarm Enabled Bit 3: 1 = Force Demod A Alarm Enabled Bit 4: 1 = Mod B Alarm Enabled Bit 5: 1 = Force Mod B Alarm Enabled Bit 6: 1 = Demod B Alarm Enabled Bit 7: 1 = Force Demod B Alarm Enabled
<1>	Switch Alarm Masks	1 = Enabled, 0 = Masked Off Bit 0: 1 = Switch Power 1 Alarm Enabled Bit 1: 1 = Switch Power 2 Alarm Enabled Bit 2: 1 = Switch Firmware Error Enabled Bit 3: 1 = Switch NV Alarm Bit 4: 1 = Switch Internal Alarm Enabled Bit 5:.7: unused, return 0
<2>	Spare Current Alarms	Always 0

# Opcode: <2289h> Command OMS11 Switch Alarms Masks

Comn	nand Data Field (4 Bytes):	
<1>	External Alarm Masks	1 = Enabled, 0 = Masked Off
		Bit 0: 1 = Mod A Alarm Enabled
		Bit 1: 1 = Force Mod A Alarm Enabled
		Bit 2: 1 = Demod A Alarm Enabled

		Bit 3: 1 = Force Demod A Alarm Enabled Bit 4: 1 = Mod B Alarm Enabled Bit 5: 1 = Force Mod B Alarm Enabled Bit 6: 1 = Demod B Alarm Enabled Bit 7: 1 = Force Demod B Alarm Enabled
<1>	Switch Alarm Masks	1 = Enabled, 0 = Masked Off Bit 0: 1 = Switch Power 1 Alarm Enabled Bit 1: 1 = Switch Power 2 Alarm Enabled Bit 2: 1 = Switch Firmware Error Enabled Bit 3: 1 = Switch NV Alarm Enabled Bit 4: 1 = Switch Internal Alarm Enabled Bit 5:.7: unused, 0 filled
<2>	Spare Current Alarms	0 filled

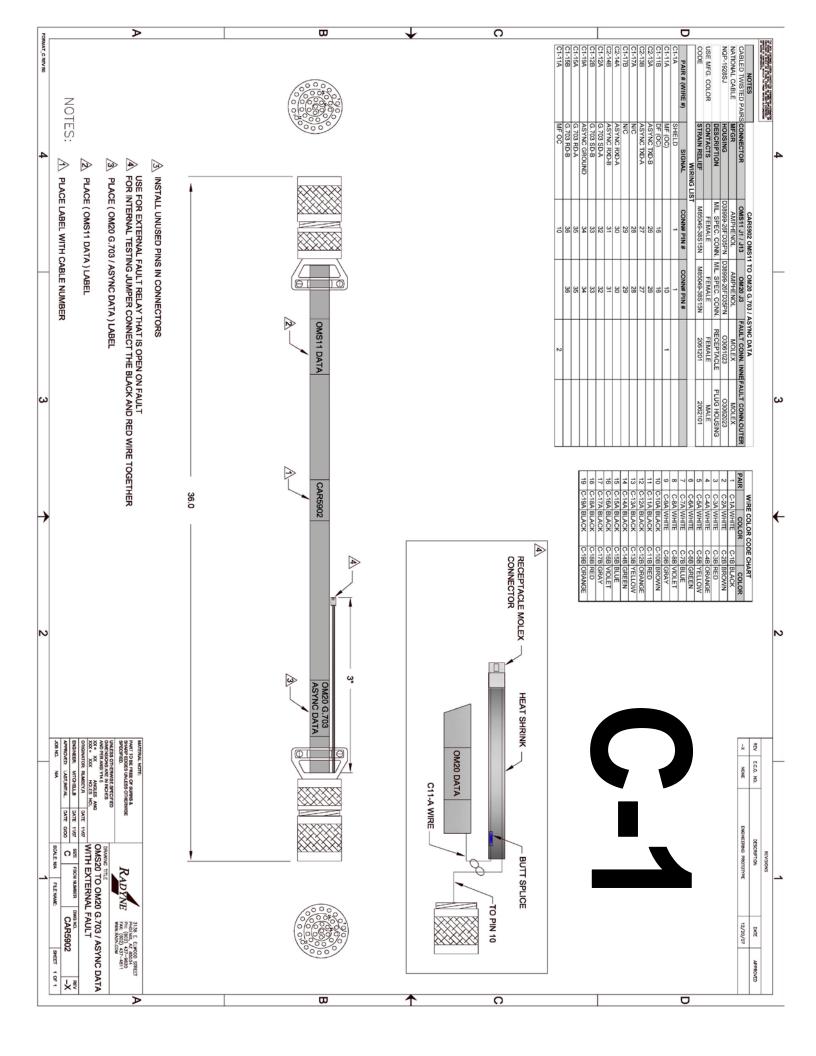


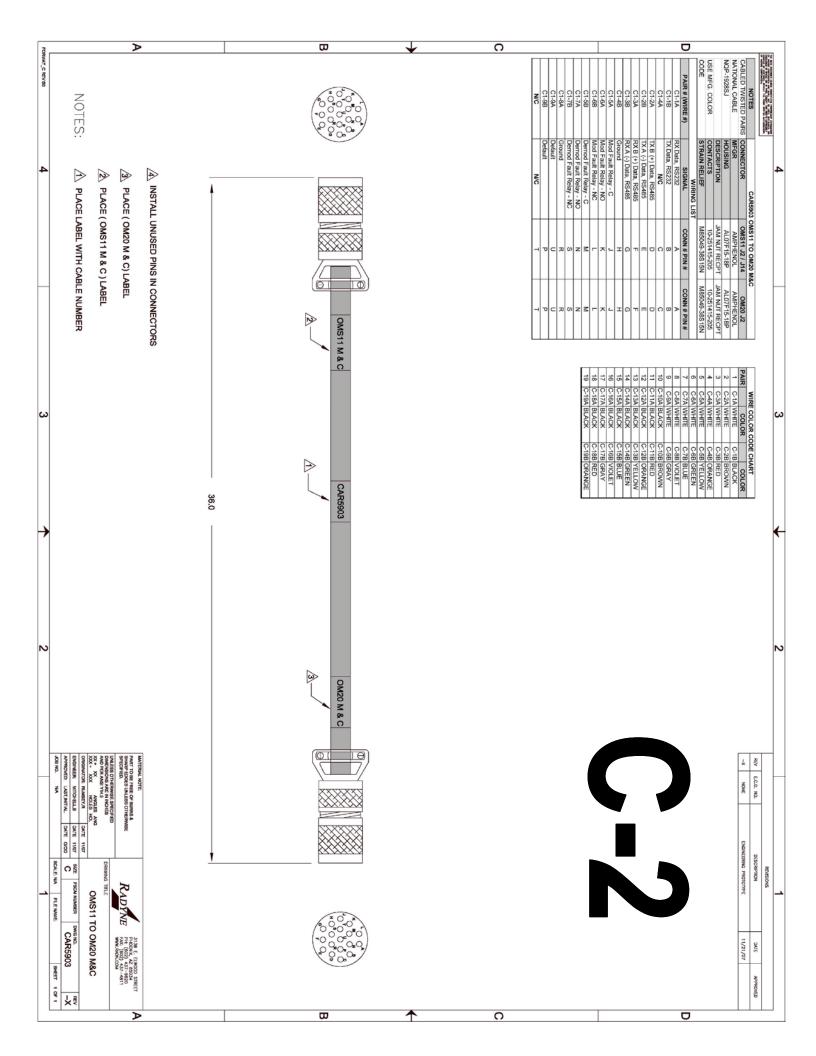
## Interconnecting Cable Drawings

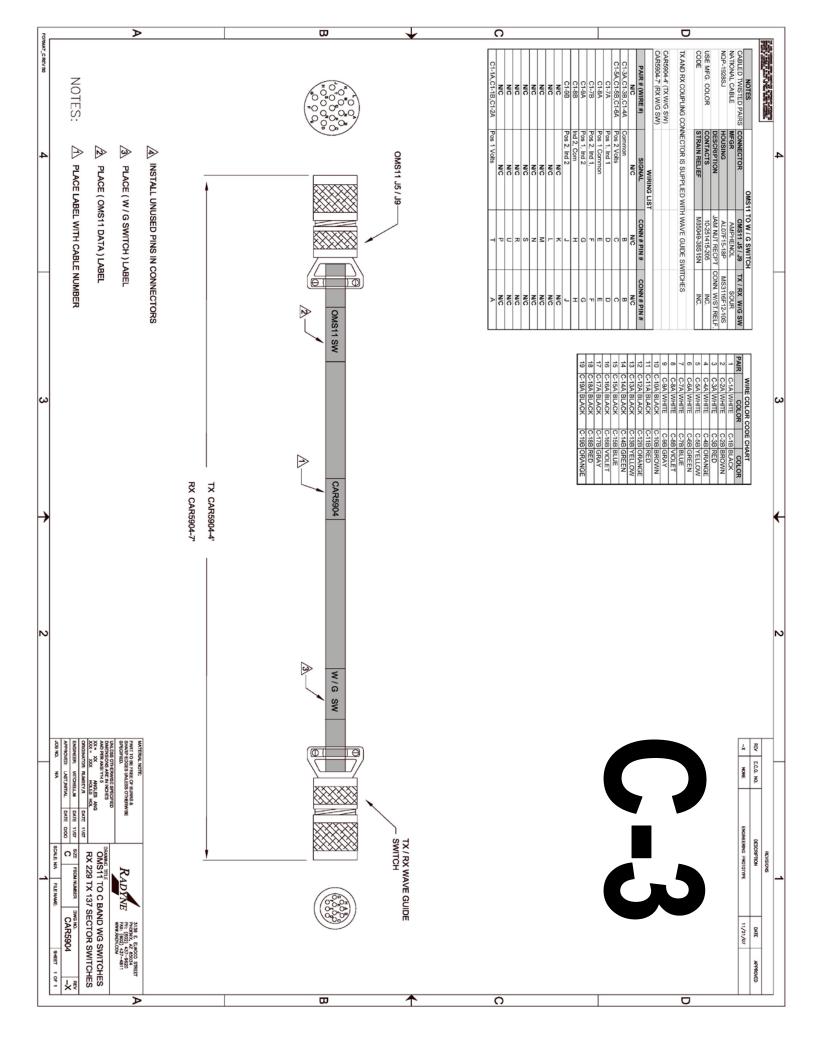


The following drawings are included or can be supplied with the OMS11 System.

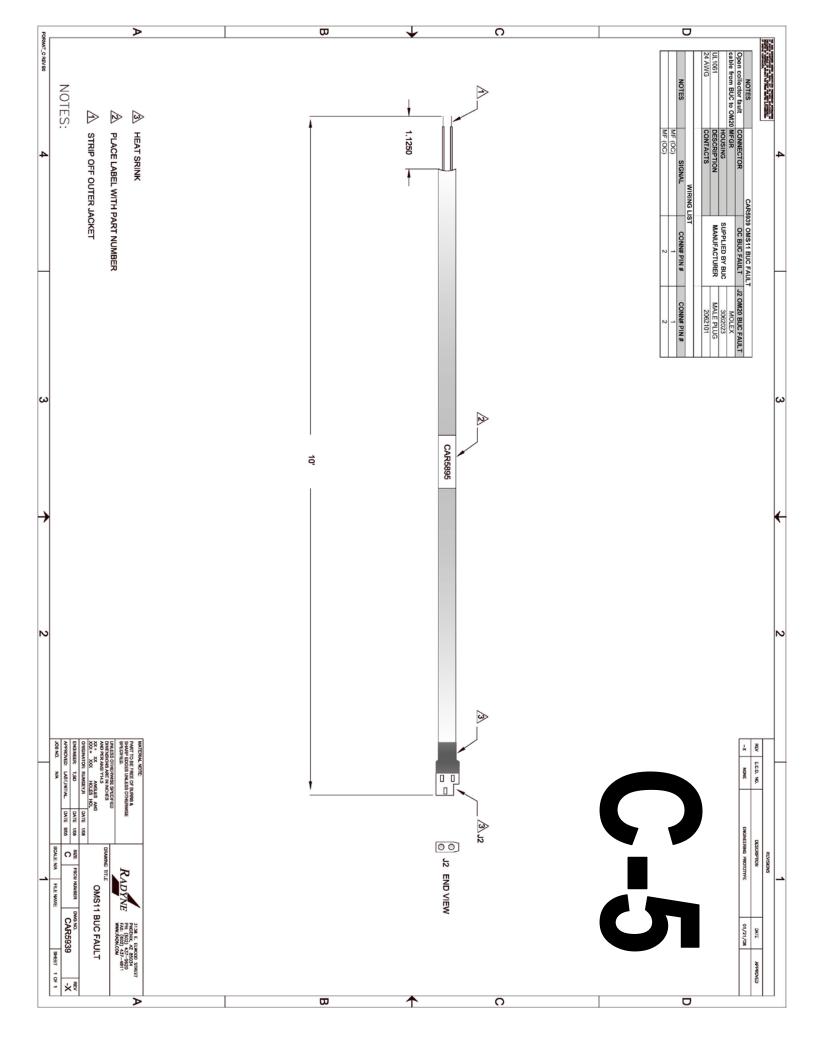
- C-1. CAR5902 OMS11 to OM20 G.703-ASYNC DATA
- C-2. CAR5903 OMS11 to OM20 M&C
- C-3. CAR5904 OMS11 to Waveguide Switches
- C-4. CAR5918 OMS11 t oOM20 EIA530 DATA
- C-5. CAR5939 BUC Fault Codan







2	>	Φ	$\checkmark$	C		D	Internet
FORMAT_C REV BO	NOTES:					NOTES   CABLED TWISTED PAIRS   CON     NATIONAL CABLE   MFG   MFG     NAP-1928SJ   HOU   DES     USE MFG. COLOR   CODE   STR     PAIR # MIRE #)   PAIR # MIRE #)   FOR # MIRE #)	
4						SIGNINECTOR CMS MEGR CMP HOUSING CMS DESCRIPTON ML STE CONTACTS M85049 STRAIN RELIEF M85049 STRAIN RELIEF M85049	4
	USE FOR EXTERNAL FAULT RELAY THA FOR INTERNAL TESTING JUMPER CONN PLACE ( OM20 EIA 530 DATA ) LABEL PLACE ( OMS11 DATA ) LABEL PLACE LABEL WITH CABLE NUMBER			11   17   18     18   18   18     20   20   20     21   21   21     22   22   22     23   23   23     26   26   26     27   28   26     28   27   26     29   27   27     30   30   27     31   31   31     34   34   34		CARS918 OMS11 TO OM20 EA530 DATA     OMS11 J13   OM20 J2   FAULT COM     AMP-FENCL   AMP-FENCL   MOL     D3899-26FD35PM   D3899-26FD35PM   C0308     ML <spec.conn.< td="">   ML<spec.conn.< td="">   RECEPE     ME.SPEC.VIN.   ML<spec.conn.< td="">   RECEPE     MB5049-38515N   M85049-38515N   2061     ST   CONN# PIN #   CONN# PIN #</spec.conn.<></spec.conn.<></spec.conn.<>	
ω	36.0 USE FOR EXTERNAL FAULT RELAY THAT IS OPEN ON FAULT FOR INTERNAL TESTING JUMPER CONNECT THE BLACK AND RED WIRE TOGETHER PLACE ( OM20 EIA 530 DATA ) LABEL PLACE ( OMS11 DATA ) LABEL PLACE LABEL WITH CABLE NUMBER			N		530 DATA FAULT CONN. UNVER FAULT CONN. OUTER MOLEX 03081023 CONEX RECEPTACLE PLUG HOUSING RECEPTACLE PLUG HOUSING FEMARLE 2061201 2062101	ω
<b>→</b>	IRE TOGETHER	CAR5918	[		8 C-64/ WHTE 9 C-64/ WHTE 10 C-104/8 LACK 11 C-114/8 LACK 12 C-134/8 LACK 13 C-134/8 LACK 14 C-144/8 LACK 15 C-154/8 LACK 16 C-164/8 LACK 17 C-174/8 LACK 18 C-164/8 LACK		←
2				RECEPTACLE MOLEX	C-88 VICULT C-98 BROWY C-108 BROWY C-108 BROW C-198 RED C-138 VELLOW C-138 VELLOW C-138 VELLOW C-138 IUTOLET C-178 GRAV C-198 RED C-198 ORANGE	CODE CHART COLOR C-18 BLACK C-28 BROWN C-28 BROWN C-28 IVELLOW C-38 VELLOW C-38 VELLOW C-38 IVELLOW	2
-	Voi 000 Valuation Indexenti In	3" OM20 EIA 530 DATA		HEAT SHRINK		× 5	82
	NDTE:     DB:   PRE:     DD:   PRE:     PRE:   PRE:		C11-A WIRE	OM20 DATA			nrc
	RADYNE THE OMS20 TO OM20 EIA 530 DATA WITH EXTERNAL FAULT C C For Namer CAR5918 SOLE NA FALLWARE 9618		m Exxx	-BUTT SPLICE	4		RDVISIONS 1
							ADDOPOVED







Α		
А	Ampere	
AC	Alternating Current	
ADC	Analog to Digital Converter	
AGC	Automatic Gain Control	
AIS	Alarm Indication System. A signal comprised of all binary 1s.	
AMSL	Above Mean Sea Level	
ANSI	American National Standards Institute	
ASCII	American Standard Code for Information Interchange	
ASIC	Application Specific Integrated Circuit	
ATE	Automatic Test Equipment	
	В	
BER	Bit Error Rate	
BERT	Bit Error Rate Test	
Bit/BIT	Binary Digit or Built-In Test	
BITE	Built-In Test Equipment	
bps	Bits Per Second	
BPSK	Binary Phase Shift Keying	
BUC	Block Upconverter	
Byte	8 Binary Digits	

	С		
С	Celsius		
CATS	Computer Aided Test Software		
CA/xxxx	Cable Assembly		
CD-ROM	Compact Disk – Read Only Memory		
CLK	Clock		
cm	Centimeter		
СОМ	Common		
CPU	Central Processing Unit		
CRC	Cyclic Redundancy Check. A system of error checking performed at the transmitting and receiving stations.		
CW	Continuous Wave		
C/N	Carrier to Noise Ratio		
	D		
DAC	Digital to Analog Converter		
dB	Decibels		
dBc	Decibels Referred to Carrier		
dBm	Decibels Referred to 1.0 milliwatt		
DC	Direct Current		
Demod	Demodulator or Demodulated		
DPLL	Digital Phase Locked Loop		
DVB	Digital Video Broadcast		
D & I	Drop and Insert		
E			
E <sub>b</sub> /N <sub>0</sub>	Ratio of Energy per bit to Noise Power Density in a 1 Hz Bandwidth.		
EEPROM	Electrically Erasable Programmable Read Only Memory		
EIA	Electronic Industries Association		
EMI	Electromagnetic Interference		
ESC	Engineering Service Circuits		
ES-ES	Earth Station to Earth Station Communication		
ET	Earth Terminal		

	F		
F	Fahrenheit		
FAS	Frame Acquisition Sync. A repeating series bit, which allow acquisition of a frame.		
FCC	Federal Communications Commission		
FEC	Forward Error Correction		
FIFO	First In, First Out		
FPGA	Field Programmable Gate Arrays		
FW	Firmware		
	G		
g	Force of Gravity		
GHz	Gigahertz		
GND	Ground		
	Н		
HSSI	High Speed Serial Interface		
HW	Hardware		
Hz	Hertz (Unit of Frequency)		
	1		
IBS	Intelsat Business Services		
IDR	Intermediate Data Rate		
I/O	Input/Output		
IEEE	International Electrical and Electronic Engineers		
IESS	INTELSAT Earth Station Standards		
IF	Intermediate Frequency		
INTELSAT	International Telecommunication Satellite Organization		
ISO	International Standards Organization		
1 & Q	Analog In-Phase (I) and Quadrature Signals (Q)		
	J		
J	Joule		

	К	
Kbps	Kilobits per Second	
Kbps	Kilobytes per Second	
kg	Kilogram	
kHz	Kilohertz	
Ksps	Kilosymbols per Second	
	L	
LCD	Liquid Crystal Display	
LED	Light Emitting Diode	
LO	Local Oscillator	
	M	
mA	Milliampere	
Mbps	Megabits per Second	
MFAS	Multi-Frame Acquisition Sync. See FAS.	
MHz	Megahertz	
MIB	Management Information Base	
Mod	Modulator or Modulated	
ms or msec	Millisecond	
M&C	Monitor and Control	
	N	
NC	Normally Closed	
NO	Normally Open	
ns	Nanoseconds	
NVRAM	Non-Volatile Random Access Memory	
N/C	No Connection or Not Connected	
	0	
OQPSK	Offset Quadrature Phase Shift Keying	
P		
PC	Personal Computer	
PD Buffer	Plesiochronous/ Doppler Buffer	
PLL	Phase Locked Loop	
ppb	Parts per Billion	
ppm	Parts per Million	
P/N	Part Number	
Q		
QAM	Quadrature Amplitude Modulation	
QPSK	Quadrature Phase Shift Keying	

	R		
RAM	Random Access Memory		
RF	Radio Frequency		
ROM	Read Only Memory		
rms	Root Mean Square		
RU	Rack Unit. 1 RU = 1.75"/4.45 cm		
Rx	Receive (Receiver)		
RxD	Receive Data		
R-S	Reed-Solomon Coding. Reed-Solomon codes are block-based error correcting codes with a wide range of applications in digital communications and storage.		
	S		
SEQ	Sequential		
SYNC	Synchronize		
	Т		
TBD	To Be Designed or To Be Determined		
ТМ	Technical Manual		
TPC	Turbo Product Codes		
TRE	Trellis		
Тх	Transmit (Transmitter)		
TxD	Transmit Data		
	U		
UART	Universal Asynchronous Receiver/Transmitter		
UUT	Unit Under Test		
V			
V	Volts		
VAC	Volts, Alternating Current		
VCO	Voltage Controlled Oscillator		
VDC	Volts, Direct Current		
VIT	Viterbi Decoding		

WXYZ		
W	Watt	
Misc.		
μs	Microsecond	
Ohms	Ohms	
16QAM	16 Quadrature Amplitude Modulation	
8PSK	8 Phase Shift Keying	